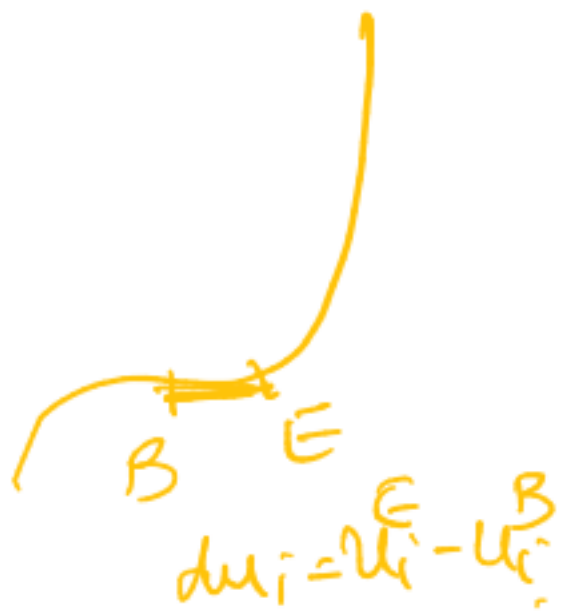
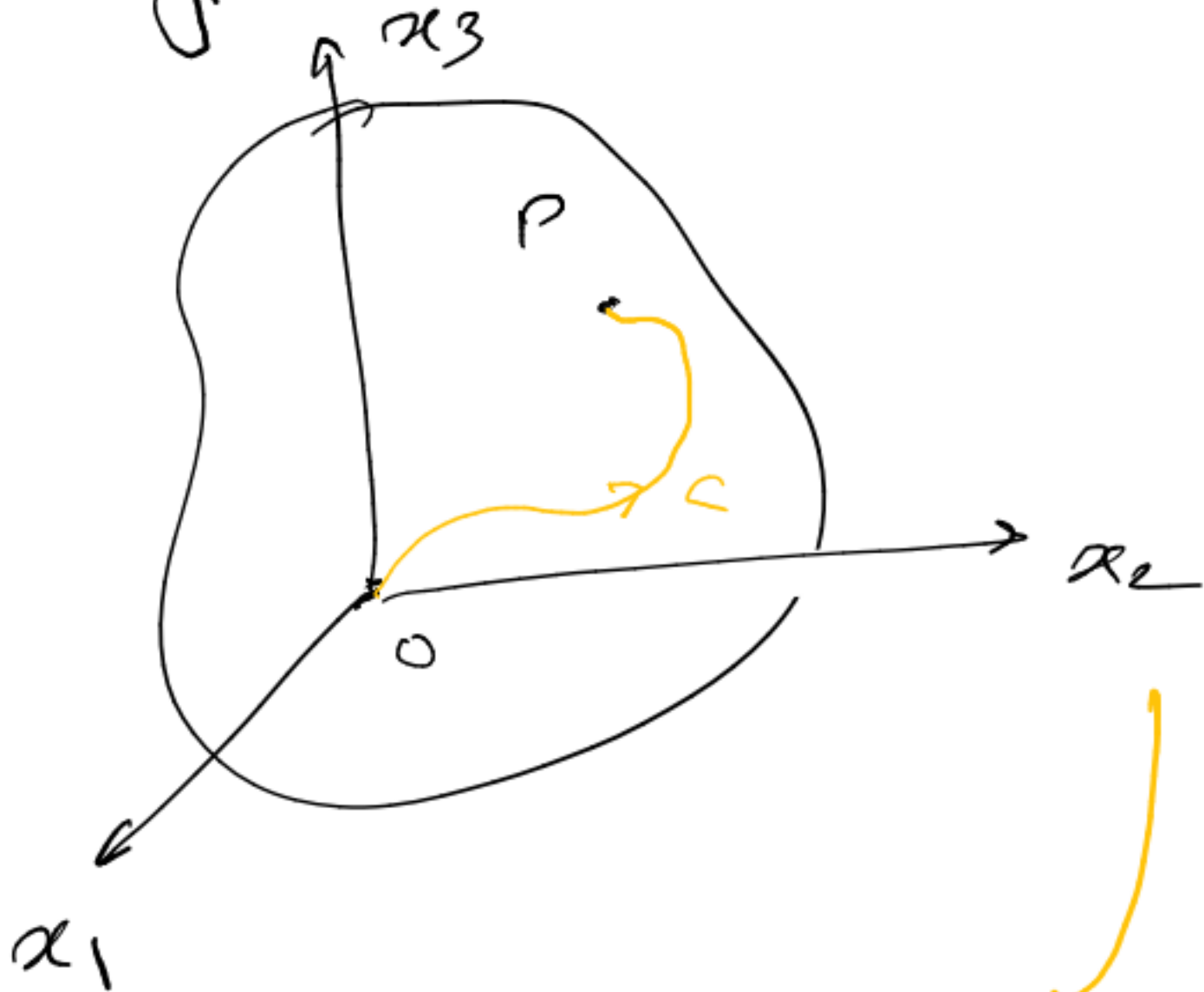


Lecture 12

Compatibility Conditions.



$$u_i^P = u_i^O + \int_C du_i$$
$$= u_i^O + \int_C \frac{\partial u_i}{\partial x_j} dx_j$$

$$u_{i,j} = \epsilon_{ij} + \omega_{ij}$$

$$U_i^P = U_i^0 + \int_C (\epsilon_{ij} + \omega_{ij}) dx_j$$

Consider

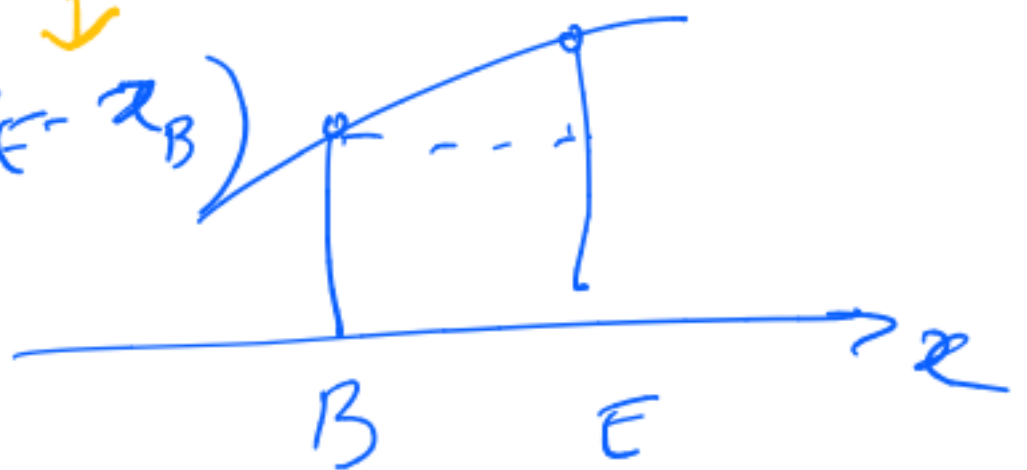
$$\int_C \omega_{ij} dx_j = \omega_{ij} x_j \Big|_0^P - \int_C x_j d\omega_{ij}$$

$$= \omega_{ij}^P x_j^P - \omega_{ij}^0 x_j^0$$

$$- \int_C x_j \omega_{ij,k} dx_k$$

$$\sum_{\text{all pieces}} x_j (\omega_{ij}^E - \omega_{ij}^B) \frac{\partial \omega_{ij}}{\partial x_k} dx_k$$

$$\omega_E - \omega_B \approx \frac{d\omega}{dx} (x_E - x_B)$$



$$\int_C \omega_{ij} dx_j = \omega_{ij}^P x_j^P - \int_C x_j \omega_{ij,k} dx_k$$

Yesterday:

$$\omega_{ij,k} = e_{ik,j} - e_{jk,i}$$

$$\int_C \omega_{ij} dx_j = \int_C x_j (e_{ik,j} - e_{jk,i}) dx_k$$

$$u_i^P = u_i^0 + \omega_{ij}^P x_j^P$$

$$+ \int_C (e_{ik} - x_j (e_{ik,j} - e_{jk,i})) dx_k$$

U_{ik}

$$u_i^P = u_i^0 + \omega_{ij}^P x_j^P + \int_C U_{ik} dx_k$$

Unless $\int_C U_{ik} dx_k$ is path-independent, we will get different u_i^P for each path that we take.

Under what conditions is $\int U_{ik} dx_k$ well-posed (path independent)?



$\int_{\tilde{c}} \tilde{F} \cdot d\tilde{x}$ is path-independent
 provided $\tilde{F} = \nabla \phi$

" $\int_{\tilde{c}} F_{ik} dx_k$ is " " "
 provided $F_{ik} = \phi_{,i;k}$

By the same token, $\int U_{ik} dx_k$ will be path-independent if $U_{ik} = \phi_{,i;k}$.

U_{ik} must be of the form $\Phi_{i,k}$.

Is it true } $U_{ik,l} \stackrel{?}{=} U_{il,k}$
 $U_{ik,l} \stackrel{\checkmark}{=} \Phi_{i,k,l}$

If U_{ik} is of the form $\Phi_{i,k}$

then $U_{ik,l} = U_{il,k} \rightarrow$ Comp. Cons.

Write this in terms of e_{ij} .

$(e_{ik} - \alpha_j (e_{ik,j} - e_{jk,i}))_{,l} =$

$(e_{il} - \alpha_j (e_{il,j} - e_{jl,i}))_{,k}$

$\Rightarrow e_{ik,l} - \alpha_{j,l} (e_{ik,j} - e_{jk,i})$
 $- \alpha_j (e_{ik,jl} - e_{jk,il}) =$
 $e_{il,k} - \alpha_{j,k} (e_{il,j} - e_{jl,i})$
 $- \alpha_j (e_{il,jk} - e_{jl,ik})$

What is $\alpha_{j,k} = \frac{\partial x_j}{\partial x_k}$

$$\left. \begin{aligned} \frac{\partial x_1}{\partial x_1} &= 1 \\ \frac{\partial x_2}{\partial x_1} &= 0 \\ \frac{\partial x_3}{\partial x_1} &= 0 \end{aligned} \right\} \frac{\partial x_j}{\partial x_k} = \delta_{jk}.$$

$$\alpha_j \left(e_{ik,jl} - e_{jk,il} - e_{il,jk} + e_{jl,ik} \right) = 0$$

for all α_j .

This implies: $() = 0$

$$e_{ik,jl} - e_{jk,il} - e_{il,jk} + e_{jl,ik} = 0.$$

Compatibility Equation:

$$e_{ij,kl} + e_{kl,ij} - e_{ik,jl} - e_{jl,ik} = 0$$

↳ There are $3^4 = 81$ such eqns.

If a given strain field e_{ij} does not satisfy these 81 conditions, there is no u_i for

which
$$e_{ij} = \frac{u_{i,j} + u_{j,i}}{2}$$

Next: out of these 81, only 6 will survive & out of these 6 only 3 are indep.